

# Computing Solution Concepts

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Computational Game Theory  
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## Notation

- $a_i^j$  : action (pure strategy) number  $j$  of player  $i$ .
- $a_{-i}$ : generic tuple of actions for players other than  $i$ .
- $s_i^j$  : probability that mixed strategy  $s_i$  assigns to action number  $j$  of player  $i$ .
- $\sum_k u_1(a_1^j, a_2^k) \cdot s_2^k$  is the utility for player 1 of playing pure strategy  $a_1^j$  against mixed strategy  $s_2^k$ .

# Linear Programming

A **linear program** is defined by:

- a set of real-valued variables
- a linear objective function
  - a weighted sum of the variables
- a set of linear constraints
  - the requirement that a weighted sum of the variables must be greater than or equal to some constant

# Linear Programming

Given  $n$  variables and  $m$  constraints, variables  $x$  and constants  $w$ ,  $a$  and  $b$ :

$$\begin{aligned} & \text{maximize} && \sum_{i=1}^n w_i x_i \\ & \text{subject to} && \sum_{i=1}^n a_{ij} x_i \leq b_j && \forall j = 1 \dots m \\ & && x_i \in \{0, 1\} && \forall i = 1 \dots n \end{aligned}$$

- These problems can be solved in **polynomial time** using interior point methods.
  - Interestingly, the (worst-case exponential) **simplex method** is often faster in practice.

# Lecture Overview

- 1 Recap
- 2 Linear Programming
- 3 Computational Problems Involving Maxmin**
- 4 Domination
- 5 Fun Game
- 6 Iterated Removal of Dominated Strategies
- 7 Computational Problems Involving Domination

# Computing equilibria of zero-sum games

$$\begin{array}{ll}
 \text{minimize} & U_1^* \\
 \text{subject to} & \sum_{a_2 \in A_2} u_1(a_1, a_2) \cdot s_2^{a_2} \leq U_1^* \quad \forall a_1 \in A_1 \\
 & \sum_{a_2 \in A_2} s_2^{a_2} = 1 \\
 & s_2^{a_2} \geq 0 \quad \forall a_2 \in A_2
 \end{array}$$

- First, identify the variables:
  - $U_1^*$  is the expected utility for player 1
  - $s_2^{a_2}$  is player 2's probability of playing action  $a_2$  under his mixed strategy
- each  $u_1(a_1, a_2)$  is a constant.

# Computing equilibria of zero-sum games

Now let's interpret the LP:

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- $s_2$  is a valid probability distribution.

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- $U_1^*$  is as small as possible.



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 & && \sum_{a_2 \in A_2} s_2^{a_2} = 1 \\
 & && s_2^{a_2} \geq 0 && \forall a_2 \in A_2
 \end{aligned}$$

- Player 1's expected utility for playing each of his actions under player 2's mixed strategy is no more than  $U_1^*$ .
  - Because  $U_1^*$  is minimized, this constraint will be tight for some actions: the support of player 1's mixed strategy.

# Computing equilibria of zero-sum games

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 & \sum_{a_2 \in A_2} s_2^{a_2} = 1 \\
 & s_2^{a_2} \geq 0 \quad \forall a_2 \in A_2
 \end{array}$$

- This formulation gives us the minmax strategy for player 2.
- To get the minmax strategy for player 1, we need to solve a second (analogous) LP.

# Computing Maxmin Strategies in General-Sum Games

Let's say we want to compute a maxmin strategy for player 1 in an arbitrary 2-player game  $G$ .

# Constraints for determining whether $s_i$ is strictly dominated by any mixed strategy

$$\sum_{j \in A_i} p_j u_i(a_j, a_{-i}) > u_i(s_i, a_{-i}) \quad \forall a_{-i} \in A_{-i}$$

$$p_j \geq 0 \quad \forall j \in A_i$$

$$\sum_{j \in A_i} p_j = 1$$

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- **What's wrong** with this program?

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$$p_j \geq 0 \quad \forall j \in A_i$$

$$\sum_{j \in A_i} p_j = 1$$

- **What's wrong** with this program?
  - **strict inequality** in the first constraint means we don't have an LP

# LP for determining whether $s_i$ is strictly dominated by any mixed strategy

$$\begin{aligned}
 & \text{minimize} && \sum_{j \in A_i} p_j \\
 & \text{subject to} && \sum_{j \in A_i} p_j u_i(a_j, a_{-i}) \geq u_i(s_i, a_{-i}) && \forall a_{-i} \in A_{-i} \\
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- This is clearly an LP. **Why is it a solution** to our problem?
  - if a solution exists with  $\sum_j p_j < 1$  then we can add  $1 - \sum_j p_j$  to some  $p_k$  and we'll have a dominating mixed strategy (since utility was assumed to be positive everywhere)
- Our original approach works for very weak domination
- For weak domination we can use that program with a different objective function trick.



# Identifying strategies that survive iterated elimination

- This can be done by repeatedly solving our LPs: solving a polynomial number of LPs is still in  $\mathcal{P}$ .
  - Checking whether every pure strategy of every player is dominated by any other mixed strategy requires us to solve at worst  $\sum_{i \in N} |A_i|$  linear programs.
  - Each step removes one pure strategy for one player, so there can be at most  $\sum_{i \in N} (|A_i| - 1)$  steps.
  - Thus we need to solve  $O((n \cdot \max_i |A_i|)^2)$  linear programs.

# Computing CE

$$\sum_{a \in A | a_i \in a} p(a) u_i(a) \geq \sum_{a \in A | a_i \in a'} p(a) u_i(a'_i, a_{-i}) \quad \forall i \in N, \forall a_i, a'_i \in A_i$$

$$p(a) \geq 0$$

$$\forall a \in A$$

$$\sum_{a \in A} p(a) = 1$$

- variables:  $p(a)$ ; constants:  $u_i(a)$

# Computing CE

$$\sum_{a \in A | a_i \in a} p(a) u_i(a) \geq \sum_{a \in A | a_i \in a} p(a) u_i(a'_i, a_{-i}) \quad \forall i \in N, \forall a_i, a'_i \in A_i$$

$$p(a) \geq 0 \quad \forall a \in A$$

$$\sum_{a \in A} p(a) = 1$$

- variables:  $p(a)$ ; constants:  $u_i(a)$
- we could find the social-welfare maximizing CE by adding an objective function

$$\text{maximize: } \sum_{a \in A} p(a) \sum_{i \in N} u_i(a).$$

# Why are CE easier to compute than NE?

$$\sum_{a \in A | a_i \in a} p(a) u_i(a) \geq \sum_{a \in A | a'_i \in a} p(a) u_i(a'_i, a_{-i}) \quad \forall i \in N, \forall a_i, a'_i \in A_i$$

$$p(a) \geq 0 \quad \forall a \in A$$

$$\sum_{a \in A} p(a) = 1$$

- intuitively, correlated equilibrium has only a single randomization over outcomes, whereas in NE this is constructed as a product of independent probabilities.
- To change this program so that it finds NE, the first constraint would be

$$\sum_{a \in A} u_i(a) \prod_{j \in N} p_j(a_j) \geq \sum_{a \in A} u_i(a'_i, a_{-i}) \prod_{j \in N \setminus \{i\}} p_j(a_j) \quad \forall i \in N, \forall a'_i \in A_i.$$

- This is a nonlinear constraint!

We start with the feasibility program. Given a support profile  $\sigma = (\sigma_1, \sigma_2)$  as input (where each  $\sigma_i \subseteq A_i$ ), feasibility program TGS (for “test given supports”) finds a NE  $p$  consistent with  $\sigma$  or proves that no such strategy profile exists. In this program,  $v_i$  corresponds to the expected utility of player  $i$  in an equilibrium, and the subscript  $-i$  indicates the player other than  $i$  as usual. The complete program follows.

$$\sum_{a_{-i} \in \sigma_{-i}} p(a_{-i}) u_i(a_i, a_{-i}) = v_i \quad \forall i \in \{1, 2\}, a_i \in \sigma_i \quad (4.26)$$

$$\sum_{a_{-i} \in \sigma_{-i}} p(a_{-i}) u_i(a_i, a_{-i}) \leq v_i \quad \forall i \in \{1, 2\}, a_i \notin \sigma_i \quad (4.27)$$

$$p_i(a_i) \geq 0 \quad \forall i \in \{1, 2\}, a_i \in \sigma_i \quad (4.28)$$

$$p_i(a_i) = 0 \quad \forall i \in \{1, 2\}, a_i \notin \sigma_i \quad (4.29)$$

$$\sum_{a_i \in \sigma_i} p_i(a_i) = 1 \quad \forall i \in \{1, 2\} \quad (4.30)$$

# Linear Program for Weak Dominance

- Question: Is pure strategy  $s_i$  weakly dominated by some mixed strategy with probs  $p_1, \dots, p_j, \dots$ ?
- As with strict dominance, need to use objective function to check a strict inequality.
- Maximize  $\sum_{a_{-i}} [(\sum_{a_j} p_j \cdot u_i(a_j, a_{-i})) - u_i(s_i, a_{-i})]$

subject to  $(\sum_{a_j} p_j \cdot u_i(a_j, a_{-i})) \geq u_i(s_i, a_{-i})$  for all  $a_{-i}$

$$\begin{aligned} p_j &\geq 0 && \text{for all } j \\ \sum_j p_j &= 1 \end{aligned}$$

## Linear Program for 2-player Nash Equilibrium that doesn't work

- Solve the following constraints.

$$\sum_k u_1(a_1^j, a_2^k) \cdot s_2^k + r_1^j = U_1 \text{ for all } j \text{ indexing an action of player 1}$$

$$\sum_j u_2(a_1^j, a_2^k) \cdot s_1^j + r_2^k = U_2 \text{ for all } k \text{ indexing an action of player 2}$$

$$\sum_j s_1^j = 1, \sum_k s_2^k = 1$$

$$s_1^j \geq 0, s_2^k \geq 0, r_1^j \geq 0, r_2^k \geq 0 \quad \text{for all } j, k$$

- Why doesn't this work?
- Can make the slack variables  $r$  and  $U$  arbitrarily large.

# Linear Complementarity Program

$$\sum_k u_1(a_1^j, a_2^k) \cdot s_2^k + r_1^j = U_1 \quad \text{for all } j \text{ indexing an action of player 1}$$

$$\sum_j u_2(a_1^j, a_2^k) \cdot s_1^j + r_2^k = U_2 \quad \text{for all } k \text{ indexing an action of player 2}$$

$$\sum_j s_1^j = 1, \sum_k s_2^k = 1$$

$$s_1^j \geq 0, s_2^k \geq 0, r_1^j \geq 0, r_2^k \geq 0 \quad \text{for all } j, k$$

$$r_1^j \cdot s_1^j = 0, r_2^k \cdot s_2^k = 0 \quad \text{here } \cdot \text{ is the dot product}$$

- Why does this work?
- If  $s_1^j$  is positive (in the support of  $s_1$ ), then  $r_1^j = 0$ .
- Think of  $r_1^j$  as the incentive to switch from  $a_1^j$  to a best reply against  $s_2^k$ .
- The bad news: this is no longer a linear program.  
The book discusses the famous Lemke-Howson algorithm for solving the LCP.



# Fictitious Play

- A simple intuitive way to learn in a repeated game is also often a good way to compute a Nash equilibrium.
- In **fictitious play**, we start at a random point.
- Each player observes the average frequency with which each action was chosen by their opponents.
- Then the player chooses a best reply to the average frequency.
- If this process converges, it settles into a Nash equilibrium.
- It converges in many situations, e.g. zero-sum games.