# Deep Soccer Analytics: Learning An Action-value Function For Evaluating Soccer Players



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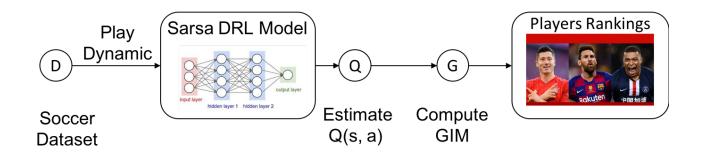


**ECML-PKDD 2020 Presentation** 

# Overview

### Learning an Action-Value Q Function for soccer player evaluation:

- Modeling *play dynamics* based on a Markov Game Process (s,a,r).
- Build a *Deep Reinforcement Learning* (DRL) model to compute action-value Q function.
- Compute a *Game Impact Metric (GIM)*.
- *Rank player* and evaluate their performance.
- *Examine* the model with a Multi-League play-by-play dataset.



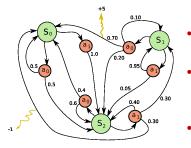
Overview

## Motivation

### Why Deep Reinforcement Learning (DRL):

Previous Model-based methods [1,2,3]:

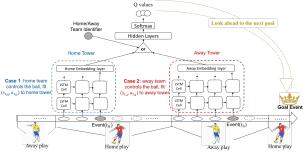
- Explicitly construct a Markov Model.
- Model building and function learning are *independent*.
- Infeasible for large dataset.



- Requires discretizing the continuous features.
- Huge state numbers (e.g., 10 features each with 10 dimension indicates  $10^{10}$  states).
- Complex transitions.

Our Sarsa DRL model:

- Model-Free RL ( no pre-built models).
- An end-to-end model (no data preprocessing, no intermediate model).
- Generalize to large dataset (mini-batch gradient descent fits dataset with any size).



[1] Routley, Kurt, and Oliver Schulte. "A Markov Game model for valuing player actions in ice hockey." Proceedings of the Thirty-First Conference on Uncertainty in Artificial Intelligence. 2015.
 [2] Schulte, Oliver, et al. "A Markov Game model for valuing actions, locations, and team performance in ice hockey." Data Mining and Knowledge Discovery 31.6 (2017): 1735-1757.
 [3] Cervone D, D'Amour A, Bornn L, Goldsberry K (2016) A multiresolution stochastic process model for predicting basketball possession outcomes. J Am Stat Assoc 111(514):585–599

Motivation

# **Preliminary Result**

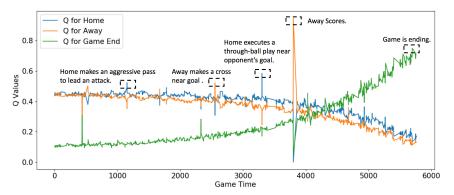
### Visualizing the Q functions learned by DRL:

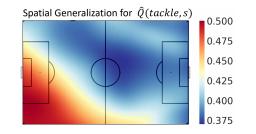
### Temporal Projection

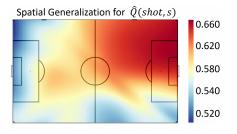
- Q values for a game between Fulham (Home) and Sheffield Wednesday (Away), which has happened on Aug. 19th, 2017.
- Q functions represents the probability of home/away team score the next goal or nobody score.

#### **Spatial Projection**

- Q functions for actions: shots and tackles.
- Q function (learned by DRL) generalizes from observed states and actions to those that have not occurred.







#### **Preliminary Result**

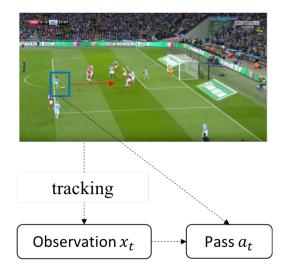
# **THANK YOU!**



## **Dataset and Preprocessing**

### A play-by-play soccer dataset for sports analytic

- Records the actions of on-the-ball players and the *spatial* and the *temporal* context features.
- *Multiple leagues*, multiple teams and players.



Name	Туре	Range	Dataset	F24
Game Time Remaining	Continuous	[0, 100]	Events	4,679,354
X Coordinate of ball	Continuous	[0, 100]	Players	5,510
Y Coordinate of ball	Continuous	[0, 100]	Games	2,976
Manpower Situation	Discrete	[-5, 5]	Teams	164
Goal Differential	Discrete	$(-\infty, +\infty)$	Leagues	10
Action	Discrete	one-hot representation	Season	2017-18
Action Outcome	Discrete	{success, failure}	Place	Europe
Velocity of ball	Continuous	$(-\infty, +\infty)$		I
Event Duration	Continuous	$[0, +\infty)$	Table 3: I	Dataset stat
Angle between ball and goal	Continuous	$[-\pi, +\pi]$	tics. The ba	
Home or Away Team	Discrete	{Home, Away}	dataset is ev	

Table 2: Complete feature list. For the feature manpower situation, negative values indicate short-handed, positive values indicate power play.

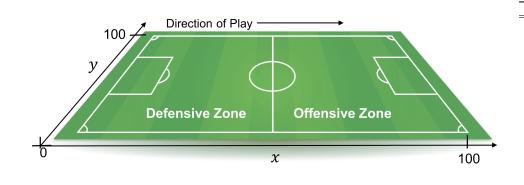
Table 3: Dataset statistics. The basic unit of this dataset is *event*, which describes the game context and the on-the-ball action of a player at a time step.

#### **Dataset and Preprocessing**

### **Dataset and Preprocessing**

### The dataset utilizes adjusted spatial coordinates

- Both the X-coordinates and Y-coordinates are adjusted to [0, +100].
- · We reverse the coordinates when the team in possession attacks towards the left
- The play flows from left to right for either team on the adjusted soccer pitch.



F=Fail, H=	F=Fail, H=Home, A=Away, T=Team who performs action, GTR = Game Time Remain, ED = Event Duration										
GTR	X	Y	MP	GD	Action	OC	Velocity	ED	Angle	Т	Reward
35m44s	87	26	Even	1	simple pass	S	(2.2, 1.7)	11.0	0.19	Н	[0,0,0]
35m42s	90	17	Even	1	standard shot	F	(1.5, -4.5)	2.0	0.11	Н	[0,0,0]
35m42s	99	44	Even	1	save	S	(0, 0)	0.0	0.06	Α	[0,0,0]
35m9s	100	1	Even	1	cross	S	(0.0, -1.3)	33.0	0.0	Н	[0,0,0]
35m7s	85	56	Even	1	simple pass	S	(-7.3, 27.6)	2.0	0.39	Н	[0,0,0]
35m5s	92	67	Even	1	simple pass	S	(3.6, 5.4)	2.0	0.28	Н	[0,0,0]
35m4s	97	50	Even	1	corner shot	S	(5.1, -16.2)	1.0	1.74	Н	[0,0,0]
35m4s	100	50	Even	1	goal	S	(0, 0)	0.0	0.0	Н	[1,0,0]
3m41s	62	96	Even	2	long ball	F	(4.5, 9.3)	9.0	0.08	Α	[0,0,0]
3m39s	19	89	Even	2	clearance	S	(-21.5, -3.2)	2.0	0.07	Н	[0,0,0]
3m35s	24	100	Even	2	throw in	S	(1.3, 2.7)	4.0	0.09	Α	[0,0,0]
3m33s	27	96	Even	2	simple pass	S	(1.1, -2.2)	2.0	0.1	Α	[0,0,0]
3m31s	12	95	Even	2	cross	S	(-7.5, -0.5)	2.0	0.07	Α	[0,0,0]
3m28s	6	46	Even	2	simple pass	S	(-1.7, -16.3)	3.0	0.79	Α	[0,0,0]
3m26s	14	48	Even	2	standard shot	S	(3.8, 1.3)	2.0	0.44	Α	[0,0,0]
3m26s	0	50	Even	2	goal	S	(0, 0)	0.0	0.0	Α	[0,1,0]

MP=Manpower, GD=Goal Difference, OC = Outcome, S=Succeed,

Table 1: A data sample featuring team scoring: a sequence of events where home team scores and then away team scores. The rewards [1,0,0] and [0,1,0] indicate the scoring event of home team and away team respectively (see Section 4.1). We skip some events in the middle due to space issues.

#### **Dataset and Preprocessing**

## **Play Dynamic in Soccer**

### A Markov model for soccer games.

- Two agents: Home and Away
- An action  $a_t$  (one-hot representation) denotes the movements of players who control the ball.
- An **observation** is a feature vector  $x_t$  specifying a value of the features.
- A game **state** records the complete sequence  $s_t \triangleq (x_t, a_{t-1}, x_{t-1}, ..., x_0)$ .
- The **reward**  $r_t$  is a vector of goal values  $g_t$  that specifies which team (Home, Away) scores.

### An action-value Q function.

- Divide a soccer game into **goal-scoring episodes**. 1) **starts** at the beginning of the game, or immediately after a goal, and 2) **terminates** with a goal or at the end of the game.
- The **next-goal Q-function** represents the probability that the home resp. away team scores the goal at the end of the current goal-scoring episode.

$$Q_{team}(s,a) = P(goal_{team} = 1 | s_t = s, a_t = a)$$

**Dataset and Preprocessing** 

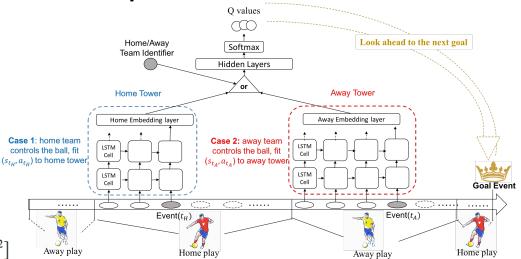
# **Model Structure**

### Two-Tower Dynamic Play LSTM (TTDP-LSTM)

- Three output nodes at each time step: \$\hat{Q}\_{home}\$, \$\hat{Q}\_{away}\$, and \$\hat{Q}\_{end}\$.
- *Two towers*: fits home and away data separately.
- **Dynamic possession-LSTM**: 1) apply a dynamic trace length. 2) trace back to the beginning of a play.
- Temporal Difference (TD) Loss:

$$\mathcal{L}(\theta) = \sum_{team \in T} \mathbb{E}\left[ (r_{team,t+1} + \hat{Q}_{team}(s_{t+1}, a_{t+1}) - \hat{Q}_{team}(s_t, a_t))^2 \right]$$

- Training settings:
  - 1) Stacked (a tow layer) LSTM
  - 2) Minibatch training.
  - 3) max trace length is 10.



**Model Structure** 

## Model Validation: Q Values

### Illustration of Temporal and Spatial Projection:

Go back to slide 4

#### **Calibration Quality for the learned Q-function:**

- Evaluate how well our learned Q-function fits the observed scoring frequencies.
- Discretized game context:
  - 1) Manpower (Short Handed (SH), Even Strength (ES), Power Play (PP)).
  - 2) Goal Differential ( $\geq$ -3, -2, -1, 0, 1, 2,  $\geq$  3).
  - 3) Period (1 (first half), 2 (second half)).
- Measures (how close they are):
- 1) Empirical Scoring Probabilities  $Q_{team}^{obs}(A) = \frac{1}{|A|} \sum_{s \in A} goal_{team}^{obs}(s)$
- 2) Estimated Scoring Probabilities  $\hat{Q}_{team}(A) = \frac{1}{|A|} \sum_{s \in A} \hat{Q}_{team}(s, a)$

Man.	Goal.	P.	A	TT_Home	TT_Away	TT_MAE	Markov_MAE
ES	-1	1	73176	0.4374	0.4159	0.0052	0.1879
ES	-1	2	96408	0.3496	0.3025	0.0782	0.1783
ES	0	1	356597	0.4437	0.4272	0.026	0.1908
ES	0	2	160080	0.356	0.3077	0.0814	0.1792
ES	1	1	88726	0.4402	0.4128	0.0335	0.1899
ES	1	2	119901	0.3459	0.295	0.077	0.1787
PP	-1	1	876	0.4366	0.4045	0.1752	0.1937
PP	-1	2	3319	0.352	0.2911	0.0668	0.1685
PP	0	1	3183	0.4414	0.403	0.1308	0.187
PP	0	2	7183	0.3579	0.2855	0.0841	0.1804
PP	1	1	1316	0.4391	0.3949	0.115	0.1825
PP	1	2	7676	0.356	0.2862	0.1121	0.1792

Table 4: Calibration Results. TT\_Home and TT\_Away report the average scoring probability  $\hat{Q}_{team}(A)$  estimated by our TTDP-LSTM model. Here we compare only Q values for pass and shot as they are frequent and well-studied actions. TT\_MAE is the Mean Absolute Error (MAE) between estimated scoring probabilities from our model and empirical scoring probabilities. For comparison, we also report a Markov\_MAE which applies the estimates from a discrete-state Markov model [Schulte et al., 2017b].

#### Model Validation: Q Values

# **Player Evaluation Metric**

### **Goal Impact Metric (GIM):**

- Compute the impact of an action by
  - 1) How much it changes the expected total reward of a player's team.
  - 2) Or the difference in expected total reward before and after the player acts.
- GIM calculates the total impact of a player's action:

$$impact^{team}(s, a, s', a') \equiv Q_{team}(s', a') - \mathbb{E}_{s', a'}[Q_{team}(s', a')|s, a]$$
$$GIM^{i}(D) \equiv \sum_{s, a, s', a'} n[s, a, s', a', pl' = i; D] \cdot impact^{team}(s, a, s', a')$$

### Q Value Above Average Replacement (QAAR):

• The QAAR metric compares 1) the expected total future reward given that player i acts next, to 2) the expected total future reward given that a random replacement player acts next:

$$QAAR^{i}(D) \equiv \sum_{s,a} n[s, a, pl' = i; D] \Big( \mathbb{E}_{s',a'}[Q_{team}(s', a'|s, a, pl' = i)] - \\ \mathbb{E}_{s',a'}[Q_{team}(s', a')|s, a] \Big)$$

$$Proposition: For each player i recorded in our play-by-play dataset D, \\ QAAR^{i}(D) = GIM^{i}(D):$$

**Player Evaluation Metric** 

## **Mimic Decision Tree**

### **Understanding Impact Values with Mimic Decision Tree:**

- Target: Understand why some actions have large impacts under certain game contexts.
- Method: Mimic Decision Tree.
  - 1) Feed states and actions into a CART to fit the impact values via supervised learning.
  - 2) Compute the *feature importance* with the learned tree.
- Some results (Top 10 important features for shot and pass):

Feature	Influence	Feature	Influence	Outcome(t)<1;	Outcome(t)<1;
X distance (t)	0.6632	X Velocity (t)	0.1355	Impact: 1.09E-2	Impact: -5.00E-4
outcome (t)	0.2275	Distance to Goal(t)	0.1264		
Y distance (t)	0.0469	Game Time Remain (t-1)	0.1082	X Coordinate(t-1)<79.15; X Distance (t)<48.15;	Time Remain(t-1)<39.45; Outcome (t-1)<1;
Game Time Remain (t)	0.0242	Game Time Remain (t)	0.0816	Impact: -2.27E-2 Impact: 9.78E-2	Impact: 4.38E-3
duration (t)	0.0062	Outcome (t)	0.0773		
X Coordinate (t-1)	0.0059	Outcome (t-1)	0.0760	X Velocity (t) Distance to Y Distance (t) Game Time	X Distance (t-1) Distance to Distance to X Velocity
Game Time Remain (t-1)	0.0035	Distance to Goal (t-1)	0.0411	<252.64; Goal (t)<=20.19; <=0.05; Remain (t)<48.82;	<37.53; Goal (t)<=28.47; Goal (t)<=31.60; (t)<=0.12;
interrupted (t)	0.0035	Angle (t)	0.0373	Impact:-1.34E-2 Impact: -3.37E-2 Impact: 3.64E-1 Impact: -1.65E-2	Impact: -2.18E-2 Impact: -1.64E-3 Impact: 4.81E-3 Impact: -4.62E-4
X velocity (t)	0.0030	Angle (t-1)	0.0298	Eis (, Bernarian tree for the impact of shot	Eis 7. Bernaries two for the impact of some
outcome (t-1)	0.0019	X Velocity (t-1)	0.0174	Fig. 6: Regression tree for the impact of shot.	Fig. 7: Regression tree for the impact of pass.

Table 5: Feature influence for the impact of shot. Table 6: Feature influence for the impact of pass.

#### Some findings:

- Shot impact significantly increases as a player approaches the goal.
- Passing impact increases with game velocity.

#### **Mimic Decision Tree**

## **Player Ranking: Case Study**

#### **Fine-Tuning:**

- **Motivation:** Different leagues have their competition level, season length, and playoff agenda.
- **Approaches:** (EFL Championship games)
  - Train a general model to evaluate actions in European soccer. 1)
  - Fine-tune the weight values from the general model to a league specific model. 2)

#### **All-Actions Assessment:**

name	team	GIM	Goals	Assists
Matej Vydra	Derby	18.017	21	4
Leon Clarke	Sheffield United	17.785	19	5
Lewis Grabban	Sunderland	16.045	12	0
Bobby De Cordova-Reid	Bristol	15.976	19	7
Diogo José Teixeira da Silva	Wolverhampton	15.707	17	5
Tom Cairney	Fulham	15.24	5	5
Ivan Cavaleiro	Wolverhampton	14.979	9	12
Stefan Johansen	Fulham	13.565	8	8
James Maddison	Norwich	13.23	14	8
Gary Hooper	Sheffield Wednesday	11.953	10	3

Table 7: 2017-2018 season top-10 Player Impact Scores for players in EFL Championship game season.

Matej Vydra tops our 2017-2018 season ٠ ranking.

#### **Action-Specific Assessment:**

• Top shot play	/ers	<ul> <li>Top passing p</li> </ul>	
name	GIM	Goal	name
Matej Vydra	4.747	21	Leon Clarke
Leon Clarke	4.024	19	Matej Vydra
Lewis Grabban	3.775	12	Bobby De Cordova-Reid
Kouassi Ryan Sessegnon	3.657	15	Chris Wood
Harry Wilson	3.135	7	Gary Hooper
Famara Diedhiou	3.015	13	Ivan Cavaleiro
Sean Maguire	2.5	10	Diogo José Teixeira da Silva
Joe Garner	2.44	10	Gary Madine
Jarrod Bowen	2.408	14	Tom Cairney
Callum Paterson	2.29	10	Conor Hourihane

bby De Cordova-Reid 5.134 7 ris Wood 4.732 1 4.694 3 ry Hooper

Top passing players

GIM

8.05

5.957

4.533

4.283

4.202

4.123

4.042

Assist

5

4

12

5

2

5

2

Table 8: Top-10 players with largest shot impact in 2017-2018 EFL Championship game season.

Table 9: Top-10 players with largest pass impact in 2017-2018 EFL Championship game season.

- Top shot players lead the goal scoring.
- Top passing players may not have leading assists.

#### **Player Ranking**

# **Player Ranking: Empirical Evaluation**

### **Comparison Player Evaluation Metrics:**

- Goal-based Metrics :
  - 1) Plus- Minus (PM): measures how much the presence of a player influences the goals of his team.
  - 2) Expected Goal (XG): weights each shot by its chance of leading to a goal.
- All-Action Metrics:
  - 1) Valuing Actions by Estimating Probabilities (VAEP) applies the difference of action values to compute the impact of on-the-ball actions.
  - 2) Scoring Impact (SI): based on a Markov model with pre-discretized spatial and temporal features.
  - 3) M-GIM: merges our home/away towers and fits all the states and actions with a single-layer network.

### **Correlations with Standard Success Measures (all players) :**

Methods	Goals	Assists	SpG	PS%	KeyP	Yel	Red
PM	0.284	0.318	0.199	0.288	0.218	0.001	-0.069
VAEP	0.093	0.290	0.121	-0.111	0.116	0.024	0.133
XG	0.422	0.173	0.328	0.164	0.278	0.534	0.034
SI	0.585	0.153	0.438	-0.140	0.052	0.114	-0.089
M-GIM	0.648	0.367	0.573	0.153	0.417	-0.110	-0.145
GIM	0.844	0.498	0.596	0.16	0.562	-0.181	-0.137

- GIM achieves *promising correlation* with most success measures.
- Our model correctly recognizes that a penalty reduces the scoring probability, influencing the overall player GIM.

**Player Ranking** 

# **Player Ranking: Empirical Evaluation**

### **Correlations with Standard Success Measures (EFL Championship players):**

Methods	Goals	Assists	SpG	PS%	KeyP	Yel	Red
PM	0.262	0.223	0.122	0.155	0.112	0.033	-0.046
VAEP	0.08	0.26	0.116	-0.126	0.137	-0.015	0.215
XG	0.420	0.165	0.394	0.149	0.254	0.578	-0.021
SI	0.574	0.124	0.408	-0.144	0.054	0.084	-0.147
M-GIM	0.629	0.309	0.551	0.171	0.388	-0.039	-0.132
GIM	0.638	0.382	0.553	-0.053	0.468	-0.026	-0.105
FT-GIM	0.736	0.585	0.569	0.082	0.592	-0.110	-0.171

- Championship League players' correlations generally decrease.
- it is more *severe* for our GIM metric.
- Fine-tuning (FT-GIM) addresses this issue.

#### **Round-by-Round Correlations:** Predicting Future From Past Performance :

