

# Dynamic Gated Graph Neural Networks for Scene Graph Generation

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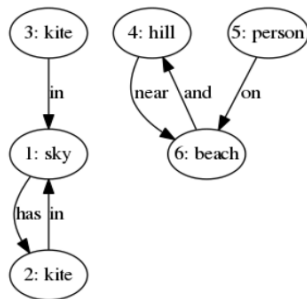
Presented by Rui Zeng

# Scene Graph Generation Task

## Scene Graph Generation Task

Given an input image: Generate a labeled digraph, whose nodes represent the objects in the image and whose edges show relationships between objects.

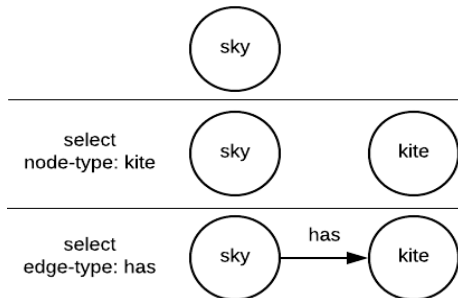
Useful in applications such as visual question answering and fine-grained recognition.



# D-GGNN: Reinforcement Learning for Scene Graph Generation

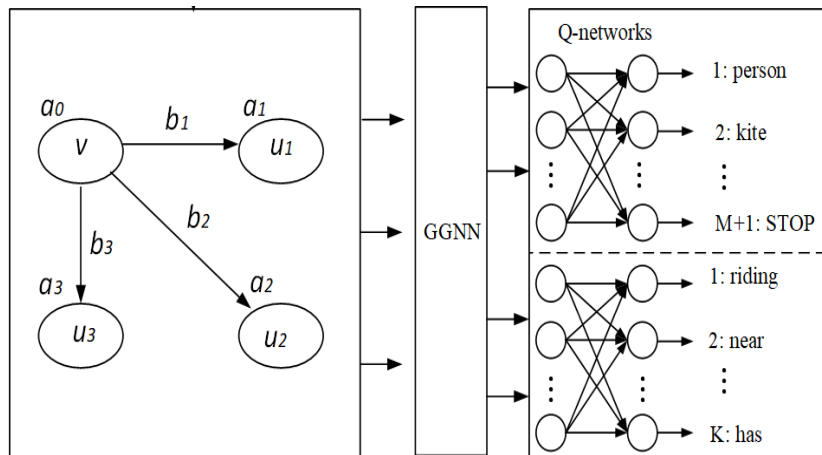
A scene graph generation algorithm needs to exploit visual contextual information.

- State = (encoding of) partial graph
- Action = expands current graph
- Reward = agreement with ground truth



# Q-value pipeline for selecting actions

- 1 Partial graph (left) is encoded using a GGNN
- 2 A Q-value neural network selects the next graph component to add.



# Q-value network for selecting actions

## State = Encoded Graph

- Feature vectors for each node  $v$ :
  - ResNet feature vector  $\hat{\mathbf{x}}_v$
  - Node embedding  $\mathbf{h}_v$ , computed by GGNN Li et al. [2015].
    - Captures link information.
- Node feature vectors are combined using a soft attention mechanism that represents how important node  $v$  is for the next decision.

A Q-function takes as input a state  $s$  and an action  $a$  and outputs expected future reward  $Q(s, a)$ .

- Implemented by deep neural network
- Trained by temporal difference learning

- The Visual Genome (VG) dataset 1.4 [Krishna et al., 2016] contains 108,077 images. Annotations provide subject-predicate-object triples.
  - e.g. man-throwing-frisbee
- 5,000 images for hyperparameter validation, 5,000 for testing.
- Preprocessing:
  - VG1.4-a uses the most frequent 150 object categories and 50 predicates Xu et al. [2017].
  - VG1.4-b uses the most frequent 1750 object categories and 347 predicates.

The goal is to find ground truth relationship triplets (subject-predicate-object). Different input information = different tasks.

- Predicate classification (PRED-CLS): location and object categories are given.
- Scene graph classification (SG-CLS) task: location of objects are given.
- Scene graph generation (SG-GEN) task: only the image is given.
- Relationship phrase detection (REL-PHRASE-DET) and Relationship detection (REL-DET) are similar to SG-GEN, applied on VG1.4-b Liang et al. [2017].
- Metric is Top-K recall ( $\text{Rec}@K$ ): the number of the ground-truth-triples hit in the top-K predictions in an image.

# Experimental Results

Model	PRED-CLS		SG-CLS		SG-GEN	
	R@50	R@100	R@50	R@100	R@50	R@100
Lu et al. [2016]	27.88	35.04	11.79	14.11	00.32	00.47
Xu et al. [2017]	44.75	53.08	21.72	24.38	03.44	04.24
D-GGNN (ours)	<b>46.85</b>	<b>55.63</b>	<b>23.80</b>	<b>26.78</b>	<b>06.36</b>	<b>07.54</b>

**Table:** VG1.4-a results for scene graph generation (SG-GEN). D-GGNN finds twice as many triplets as the previous state-of-the-art.

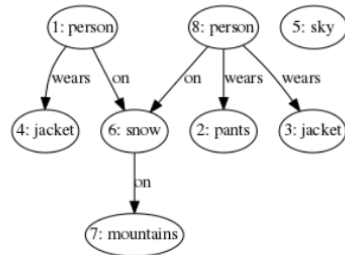
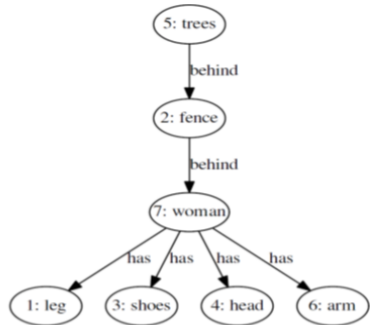
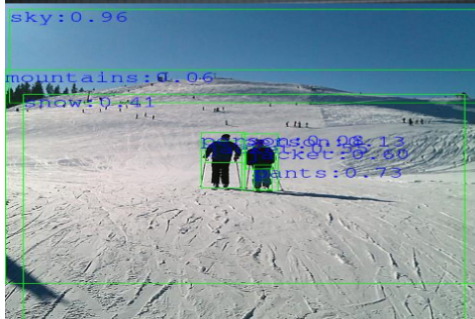
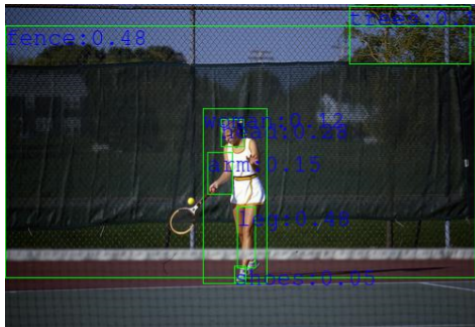
Model	REL-PHRASE-DET		REL-DET	
	R@100	R@50	R@100	R@50
CNN+RPN Simonyan and Zisserman [2014]	01.39	01.34	01.22	01.18
Faster R-CNN Ren et al. [2015]	02.25	02.19	-	-
CNN+TRPN Ren et al. [2015]	02.52	02.44	02.37	02.23
Lu et al. [2016]	10.23	09.55	07.96	06.01
VRL Liang et al. [2017]	16.09	14.36	13.34	12.57
D-GGNN (ours)	<b>18.21</b>	<b>15.78</b>	<b>14.85</b>	<b>14.22</b>

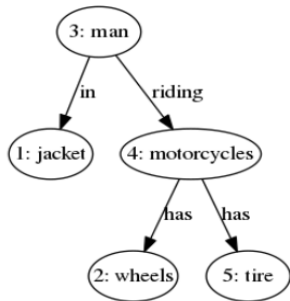
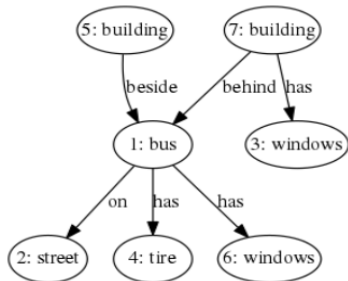
**Table:** On VG1.4-b results on variants of the scene graph generation task. D-GGNN shows an improvement over the most recent baseline, and almost double for the older methods.



# Conclusion

- Scene graph generation is an important part of scene understanding.
- We utilized a deep Reinforcement learning framework to sequentially generate a scene graph for an input image.
- New idea: entire partial graph is encoded as state information for RL.
  - A Gated Graph Neural Network computes node embeddings that capture relational information.
- We presented a generative deep architecture for graph-structured information from data sources (e.g. image, videos, text, program).
- Future Work: Evaluate in more applications, e.g. Visual Question Answering.
- We have a couple more scene graphs to show.





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