Monitoring Creatures Great and Small: Computer Vision Systems for Looking at Grizzly Bears, Fish, and Grasshoppers

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#### Captivating Cinema







video: Prof. Larry Dill, SFU Biological Sciences

#### Computer Vision for Data Collection

- "Looking at Animals" problems
  - Sifting through video to find animals
  - Determining what the animals are up to
  - Classifying species of animals
- Symbiotic relationship
  - Natural scientists receive data
  - Computer scientists receive
    - real-world datasets
    - ground truth for quantifiable success/failure





#### Outline

- Detection of animals in video
  - Grizzly bears
- Analyzing animal behaviours
  - Grasshoppers
- Recognizing animal species
  - Fish











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## Grizzly Bear Monitoring

- New eco-tourism site on salmon spawning river
  - Grizzly bears feed on salmon
  - Will human presence negatively impact bears?
- "Bearcam" deployed to watch bears on-site in northern Yukon







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Ni'iinlii Njik Park





#### Bearcam



Bearcam system recorded approx. 4h video per day for 15 days





#### **Bear Detection**



- Bears have distinct shape and pattern of motion
  - extract image gradients and background difference
  - build classifier to detect bears





#### Classifier









pos. gradient

neg. gradient

pos. back. sub.

neg. back. sub.

- Build bear detector using variant of AdaBoost (Viola-Jones)
  - A set of weak learners is built from thresholded background subtraction and gradient features

$$h_t(x) = p_t f_t(x) < p_t \theta_t$$





#### Results

- Crop windows from video frames
- Training set
  - 451 windows containing bears
  - 45100 without bears
- Test set
  - 400 bear windows
  - 40000 without







#### **Results on Frames**

- Run classifier on entire frame, take highest response
- Same training set
  - bootstrap negative set
- Test set

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- 405 frames with at least I bear
- I 6000 with none
- detect 76% at 0.001 FPPI
- detect 88% at 0.01 FPPI



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## Understanding Insect Actions

- How are grasshoppers' actions affected by spiders?
  - Predator-prey relationship
- Environment variables
  - Temperature
  - Light

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- Presence of food
- Collect data on grasshopper movement rates and actions
  - Lab environment, glass case
  - Calibrated stereo cameras







#### Top CameraBottom Camera



 Background subtraction tracker in each camera

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### **Clustering with Action Features**

- Smooth the 3D track
- For each non-overlapping window of size w of track compute the difference between x(t) and  $x(t+\Delta t)$
- Use spectral clustering on these features







#### **Clustering Results**



- Cluster purity measured
- 3530 hand-labelled frames





### **Clustering Visualization**

- Take all frames in "jump" cluster
- Show all such clips in one shorter video
  - Minimize spatial/temporal overlap of clips
  - Rav-Acha, Pritch, Peleg CVPR06

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#### Counting Fish



- Biologists have many hours of underwater video footage
  - Require count of fish by species
    - Use as proxy for tiger shark count
  - Currently, people must watch and manually identify/count
    - Automatic system could save many hours of labour





#### Challenges

- Video has limited resolution and is interlaced
- Underwater lighting has shifts in intensity and color
- Plants and sediment can cause false positives when detecting movement
- Fish appear with arbitrary locations and poses







#### Method overview

- I. Preprocess video frames to crop candidate subimages
- 2. Find correspondences between unknown images and known fish template images
- 3. Warp unknown images into alignment with the templates
- 4. Use support vector machines (SVMs) to classify the unknown images by fish species







## Warping examples



(a) test image



(b) template



(c) warped test image



(d) test image



(e) template





(f) warped test image



(i) warped test image



(g) test image

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(h) template

#### **Experimental results**

Automatic classification of 320 handcropped video frames of two fish species

SVM kernel	no warping	warped
linear	84%	90%
polynomial	81%	86%





some misclassifications



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# Thank you



