

Synchronization

- Now that you have seen locks, is that all there is?
- No, but what is the "right" way to build a parallel program.
 - People are still trying to figure that out.

Compromises:

- between making it easy to modify shared variables AND
- restricting when you can modify shared variables.
- between really flexible primitives AND
- simple primitives that are easy to reason about.

- Synchronizing on a condition.
 - ➤ When you start working on a synchronization problem, first define the mutual exclusion constraints, then ask "when does a thread wait", and create a separate synchronization variable representing each constraint.
- Bounded Buffer problem producer puts things in a fixed sized buffer, consumer takes them out.
 - > What are the constraints for bounded buffer?
 - ➤ 1) only one thread can manipulate buffer queue at a time (mutual exclusion)
 - > 2) consumer must wait for producer to fill buffers if none full (scheduling constraint)
 - ➤ 3) producer must wait for consumer to empty buffers if all full (scheduling constraint)

- Locks ensure mutual exclusion
- Bounded Buffer problem producer puts things in a fixed sized buffer, consumer takes them out.
 - Synchronizing on a condition.

```
Class BoundedBuffer{
...
void* buffer[];
Lock lock;
int count = 0;
```

```
BoundedBuffer::Deposit(c){
  lock→acquire();
  while (count == n); //spin
  Add c to the buffer;
  count++;
  lock→release();
}
```

```
BoundedBuffer::Remove(c){
  lock→acquire();
  while (count == 0); // spin
  Remove c from buffer;
  count--;
  lock→release();
}
```

```
Class BoundedBuffer{
    ...
    void* buffer[];
    Lock lock;
    int count = 0;
}
```

```
BoundedBuffer::Deposit(c){
   while (count == n); //spin
   lock→acquire();
   Add c to the buffer;
   count++;
   lock→release();
}
```

```
BoundedBuffer::Remove(c){
  while (count == 0); // spin
  lock→acquire();
  Remove c from buffer;
  count--;
  lock→release();
}
```

```
Class BoundedBuffer{
    ...
    void* buffer[];
    Lock lock;
    int count = 0;
}
```

```
BoundedBuffer::Deposit(c){
  if (count == n) sleep();
  lock->acquire();
  Add c to the buffer;
  count++;
  lock->release();
  if(count == 1) wakeup(remove);
}
```

```
BoundedBuffer::Remove(c){
  if (count == 0) sleep();
  lock->acquire();
  Remove c from buffer;
  count--;
  lock->release();
  if(count==n-1) wakeup(deposit);
```

```
Class BoundedBuffer{
    ...
    void* buffer[];
    Lock lock;
    int count = 0;
}
```

```
BoundedBuffer::Deposit(c){
  lock→acquire();
  if (count == n) sleep();
  Add c to the buffer;
  count++;
  if(count == 1) wakeup(remove);
  lock→release();
```

```
BoundedBuffer::Remove(c){
  lock→acquire();
  if (count == 0) sleep();
  Remove c from buffer;
  count--;
  if(count==n-1) wakeup(deposit);
  lock→release();
```

```
Class BoundedBuffer{
    ...
    void* buffer[];
    Lock lock;
    int count = 0;
}
```

```
BoundedBuffer::Deposit(c){
    while(1) {
        lock→acquire();
        if(count == n) {
            lock->release();
            continue;}
        Add c to the buffer;
        count++;
        lock→release();
        break;
```

```
BoundedBuffer::Remove(c){
  while(1) {
   lock→acquire();
   if (count == 0) {
     lock->release();
     continue:
   Remove c from buffer;
   count--;
   lock→release();
    break:
```

Introducing Condition Variables

- Correctness requirements for bounded buffer producerconsumer problem
 - Only one thread manipulates the buffer at any time (mutual exclusion)
 - Consumer must wait for producer when the buffer is empty (scheduling/synchronization constraint)
 - Producer must wait for the consumer when the buffer is full (scheduling/synchronization constraint)
- Solution: condition variables
 - An abstraction that supports conditional synchronization
 - > Condition variables are associated with a monitor lock
 - Enable threads to wait inside a critical section by releasing the monitor lock.

Condition Variables: Operations

- Three operations
 - Wait()
 - * Release lock
 - Go to sleep
 - * Reacquire lock upon return
 - Java Condition interface await() and awaitUninterruptably()
 - Notify() (historically called Signal())
 - Wake up a waiter, if any
 - Condition interface signal()
 - NotifyAll() (historically called Broadcast())
 - Wake up all the waiters
 - Condition interface signalAll()
- Implementation
 - > Requires a per-condition variable queue to be maintained
 - Threads waiting for the condition wait for a notify()

Wait() usually specified a lock to be released as a parameter

Implementing Wait() and Notify()

```
Condition::Notify(lock){
                schedLock->acquire();
                if (lock->numWaiting > 0) {
                     Move a TCB from waiting queue to ready queue;
                     lock->numWaiting--;
                schedLock->release();
Condition:: Wait(lock){
                                                   Why do we need
  schedLock->acquire();
                                                     schedLock?
  lock->numWaiting++;
  lock→release();
   Put TCB on the waiting queue for the CV;
   schedLock->release()
   switch();
   lock→acquire();
```

Using Condition Variables: An Example

- Coke machine as a shared buffer
- Two types of users
 - Producer: Restocks the coke machine
 - Consumer: Removes coke from the machine
- Requirements
 - Only a single person can access the machine at any time
 - ➤ If the machine is out of coke, wait until coke is restocked
 - If machine is full, wait for consumers to drink coke prior to restocking
- How will we implement this?
 - What is the class definition?
 - How many lock and condition variables do we need?

Coke Machine Example

```
Class CokeMachine{
    ...
    Storge for cokes (buffer)
    Lock lock;
    int count = 0;
    Condition notFull, notEmpty;
}
```

```
CokeMachine::Deposit(){
    lock→acquire();
    while (count == n) {
        notFull.wait(&lock); }
    Add coke to the machine;
    count++;
    notEmpty.notify();
    lock→release();
}
```

```
CokeMachine::Remove(){
    lock→acquire();
    while (count == 0) {
        notEmpty.wait(&lock); }
    Remove coke from to the machine;
    count--;
    notFull.notify();
    lock→release();
}
```

Coke Machine Example

Liveness issue

```
Class CokeMachine{
...
Storge for cokes (buffer)
Lock lock;
int count = 0;
Condition notFull, notEmpty;
}
```

```
CokeMachine::Deposit(){
    lock→acquire();
    while (count == n) {
        notFull.wait(&lock); }
    Add coke to the machine;
    count++;
    notEmpty.notify();
    lock→release();
}
```

```
CokeMachine::Remove(){
    lock→acquire();
    while (count == 0) {
        notEmpty.wait(&lock); }
    Remove coke from to the machine;
    count--;
    lock→release();
    notFull.notify();
}
```

Java syntax for condition variables

Condition variables created from locks

```
import java.util.concurrent.locks.ReentrantLock;
public static final aLock = new ReentrantLock();
public static ok = aLock.newCondition();
public static int count;
aLock.lock();
try {
   while(count < 16) {ok.awaitUninterruptably() }</pre>
} finally {
   aLock.unlock();
return 0;
```

Java syntax for condition variables

DON'T confuse wait with await (notify with signal)

```
import java.util.concurrent.locks.ReentrantLock;
public static final aLock = new ReentrantLock();
public static ok = aLock.newCondition();
public static int count;
aLock.lock();
try { // IllegalMonitorState exception
   while(count < 16){ok.wait()}</pre>
} finally {
   aLock.unlock();
return 0;
```

Summary

- Non-deterministic order of thread execution → concurrency problems
 - Multiprocessing
 - ❖ A system may contain multiple processors → cooperating threads/ processes can execute simultaneously
 - Multi-programming
 - Thread/process execution can be interleaved because of time-slicing
- Goal: Ensure that your concurrent program works under ALL possible interleaving
- Define synchronization constructs and programming style for developing concurrent programs
 - ❖ Locks → provide mutual exclusion
 - ❖ Condition variables → provide conditional synchronization