Parallelism Primitives

Shared Memory Primitives

Create thread

- Ask operating system to create a new "thread"
- Threads starts at specified function (via function pointer)

Memory regions

- Shared: globals and heap
- Per-thread: stack

Primitive memory operations

- Loads & stores
- Word-sized operations are atomic (if "aligned")

Various "atomic" memory instructions

- Swap, compare-and-swap, test-and-set, atomic add, etc.
- Perform a load/store pair that is guaranteed not to interrupted

Thread Creation

- Varies from operating system to operating system
 - POSIX threads (P-threads) is a widely supported standard (C/ C++)
 - Lots of other stuff in P-threads we're not using
 - Why? really design for single-core OS-style concurrency
- pthread_create(id, attr, start_func, arg)
 - "id" is pointer to a "pthread_t" object
 - We're going to ignore "attr"
 - "start_func" is a function pointer
 - "arg" is a void *, can pass pointer to anything (ah, C...)

Compare and Swap (CAS)

- Atomic Compare and Swap (CAS)
 - Basic and universal atomic operations
 - Can be used to create all the other variants of atomic operations
 - Supported as instruction on both x86 and SPARC
- Compare_and_swap(address, test_value, new_value):
 - Load [Address] -> old_value
 - if (old_value == test_value):
 - Store [Address] <- new_value
 - Return old_value
- Can be included in C/C++ code using "inline assembly"
 - Becomes a utility function

Inline Assembly for Atomic Operations

- x86 inline assembly for CAS
- From Intel's TBB source code machine/linux intel64.h static inline int64 compare and swap(volatile void *ptr, int64 test value, int64 new value) int64 result; asm volatile ("lock\ncmpxchqq %2,%1" : "=a"(result), "=m"(*(int64 *)ptr) : "q"(new value), "0"(test value), "m"(*(int64 *)ptr) : "memory"); return result; }
 - Black magic
 - Use of **volatile** keyword disable compiler memory optimizations

Thread Local Storage (TLS)

- Sometimes having a non-shared global variable is useful
 - A per-thread copy of a variable
- Manual approach:
 - Definition: int accumulator[NUM_THREADS];
 - Use: accumulator[thread_id]++;
 - Limited to NUM_THREADS, need to pass thread_id around false sharing
- Compiler supported:
 - Definition: __thread int accumulator = 0;
 - Use: accumulator++;
 - Implemented as a per-thread "globals" space
 - Accessed efficiently via %gs segment register on x86-64
 - More info: http://people.redhat.com/drepper/tls.pdf

Simple Parallel Work Decomposition

Static Work Distribution

- Sequential code
 - for (int i=0; i<SIZE; i++):
 - calculate(i, ..., ..., ...)
- Parallel code, for each thread:
 - void each_thread(int thread_id):
 - segment_size = SIZE / number_of_threads
 - assert(SIZE % number_of_threads == 0)
 - my_start = thread_id * segment_size
 - my_end = my_start + segment_size
 - for (int i=my_start; i<my_end; i++)
 - calculate(i, ..., ..., ...)
- Hey, its a parallel program!

Dynamic Work Distribution

Sequential code



- for (int i=**0**; i<**SIZE**; i++):
 - calculate(i, ..., ..., ...)
- Parallel code, for each thread:
 - int counter = 0 // global variable
 - void each_thread(int thread_id):
 - while (true)
 - int i = **atomic_add**(&counter, 1)
 - if (i >= SIZE)
 - return
 - calculate(i, ..., ...)
- Dynamic load balancing, but high overhead

Coarse-Grain Dynamic Work Distribution

- Parallel code, for each thread:

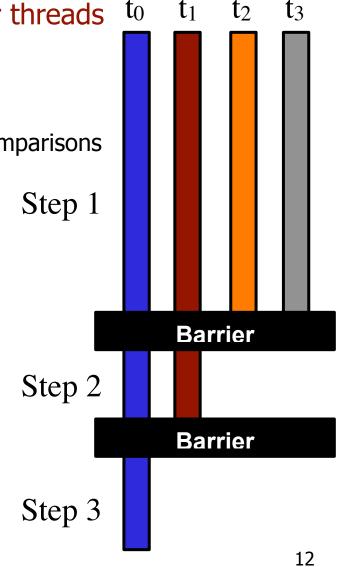
 - int num_segments = SIZE / GRAIN_SIZE
 - int counter = 0 // global variable
 - void each_thread(int thread_id):
 - while (true)
 - int i = **atomic_add**(&counter, 1)
 - if (i >= num_segments)
 - return
 - my_start = i * GRAIN_SIZE
 - my_end = my_start + GRAIN_SIZE
 - for (int j=my_start; j<my_end; j++)
 - calculate(j, ..., ..., ...)
- Dynamic load balancing with lower (adjustable) overhead

Barriers

Example: Barrier-Based Merge Sort

Merge-sort 4096 elements with four threads to

- Step #1:
 - Sort each 1/4th of array
 - (N/4)*log(N/4) = 1024*10 = 10240 comparisons
- Step #2:
 - Two N/2 merges
 - 2048 comparisons
- Step #3:
 - Final merge
 - 4096 comparisons
- Total: 3x speed up four threads
 - Parallel: 16384 comparisons
 - Sequential: ~50k comparisons

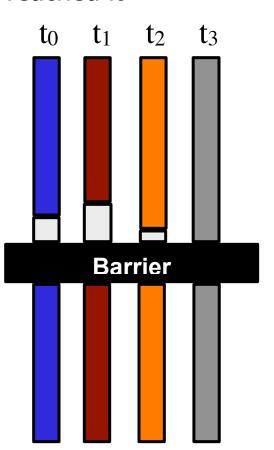


Global Synchronization Barrier

- At a barrier
 - All threads wait until all other threads have reached it
- Strawman implementation (wrong!)

```
global (shared) count : integer := P
procedure central_barrier
  if fetch_and_decrement(&count) == 1
    count := P
  else
    repeat until count == P
```

What is wrong with the above code?



Sense-Reversing Barrier

Correct barrier implementation:

```
global (shared) count : integer := P
global (shared) sense : Boolean := true
local (private) local_sense : Boolean := true

procedure central_barrier
   // each processor toggles its own sense
   local_sense := !local_sense
   if fetch_and_decrement(&count) == 1
        count := P
        // last processor toggles global sense
        sense := local_sense
   else
        repeat until sense == local_sense
```

Single counter makes this a "centralized" barrier

Other Barrier Implementations

Problem with centralized barrier

- All processors must increment each counter
- Each read/modify/write is a serialized coherence action
 - Each one is a cache miss
- O(n) if threads arrive simultaneously, slow for lots of processors

Combining Tree Barrier

- Build a log_k(n) height tree of counters (one per cache block)
- Each thread coordinates with **k** other threads (by thread id)
- Last of the k processors, coordinates with next higher node in tree
- As many coordination address are used, misses are not serialized
- O(log n) in best case

Static and more dynamic variants

• Tree-based arrival, tree-based or centralized release

Barrier Performance (from 1991)

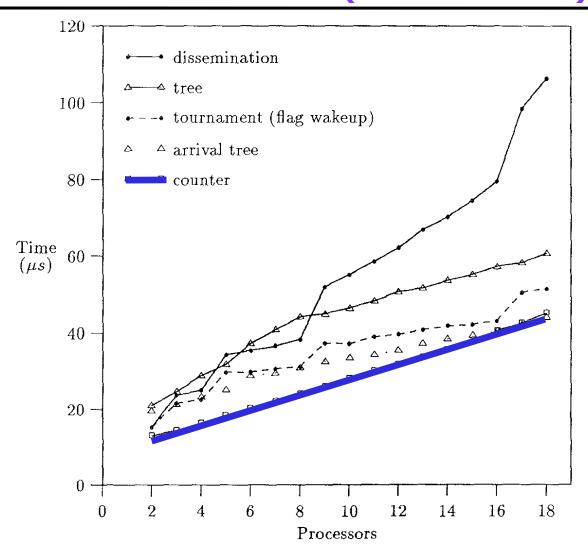


Fig. 21. Performance of barriers on the Symmetry

Locks