Data Structures & Programming

Maps

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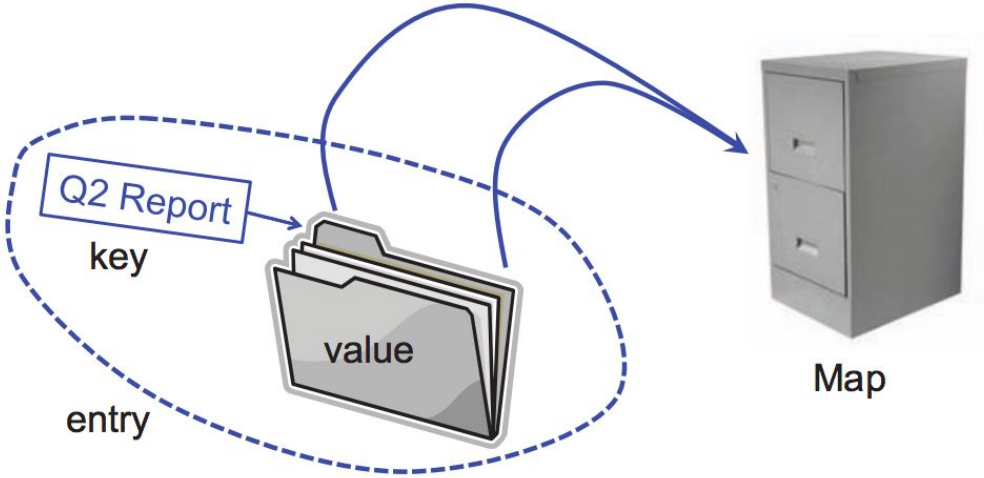
Maps



Store **key-values** (**entries**)

Locate them quickly

Keys must be **unique** (they are like indices or addresses)

Maps are sometimes called **associative store** or **associative containers**.

Map entry (key-value pair)

```
template <typename K, typename V>
class Entry {                                          // a (key, value) pair
public:                                                // public functions
  Entry(const K& k = K(), const V& v = V())            // constructor
    : _key(k), _value(v) { }
  const K& key() const { return _key; }                // get key
  const V& value() const { return _value; }            // get value
  void setKey(const K& k) { _key = k; }                // set key
  void setValue(const V& v) { _value = v; }            // set value
private:                                               // private data
  K _key;                                              // key
  V _value;                                            // value
};
```

Code Fragment 9.1: A C++ class for an entry storing a key-value pair.

Map ADT

size():	Return the number of entries in M.
empty():	Return true if M is empty and false otherwise.
find(k):	If M contains an entry $e = (k, v)$, with key equal to k, then return an iterator p referring to this entry, and otherwise return the special iterator end.
put(k, v):	If M does not have an entry with key equal to k, then add entry (k, v) to M, and otherwise, replace the value field of this entry with v; return an iterator to the inserted/modified entry.
erase(k):	Remove from M the entry with key equal to k; an error condition occurs if M has no such entry.
erase(p):	Remove from M the entry referenced by iterator p; an error condition occurs if p points to the end sentinel.
begin():	Return an iterator to the first entry of M.
end():	Return an iterator to a position just beyond the end of M.

Operation	*Output*	*Map*
empty()	**true**	$\emptyset$
put$(5,A)$	$p_1 : [(5,A)]$	$\{(5,A)\}$
put$(7,B)$	$p_2 : [(7,B)]$	$\{(5,A),(7,B)\}$
put$(2,C)$	$p_3 : [(2,C)]$	$\{(5,A),(7,B),(2,C)\}$
put$(2,E)$	$p_3 : [(2,E)]$	$\{(5,A),(7,B),(2,E)\}$
find(7)	$p_2 : [(7,B)]$	$\{(5,A),(7,B),(2,E)\}$
find(4)	end	$\{(5,A),(7,B),(2,E)\}$
find(2)	$p_3 : [(2,E)]$	$\{(5,A),(7,B),(2,E)\}$
size()	3	$\{(5,A),(7,B),(2,E)\}$
erase(5)	–	$\{(7,B),(2,E)\}$
erase(p_3)	–	$\{(7,B)\}$
find(2)	end	$\{(7,B)\}$

```
template <typename K, typename V>
class Map {                                  // map interface
public:
  class Entry;                               // a (key,value) pair
  class Iterator;                            // an iterator (and position)

  int size() const;                          // number of entries in the map
  bool empty() const;                        // is the map empty?
  Iterator find(const K& k) const;           // find entry with key k
  Iterator put(const K& k, const V& v);      // insert/replace pair (k,v)
  void erase(const K& k)                     // remove entry with key k
    throw(NonexistentElement);
  void erase(const Iterator& p);             // erase entry at p
  Iterator begin();                          // iterator to first entry
  Iterator end();                            // iterator to end entry
};
```

Code Fragment 9.2: An informal C++ Map interface (not a complete class).

List based implementation

Algorithm find(k):
Input: A key k
Output: The position of the matching entry of L, or end if there is no key k in L

```
for each position p ∈ [L.begin(), L.end()) do
    if p.key() = k then
        return p
return end
```

Algorithm erase(k):
Input: A key k
Output: None

```
for each position p ∈ [L.begin(), L.end()) do
    if p.key() = k then
        L.erase(p)
        n ← n − 1          {decrement variable storing number of entries}
```

Code Fragment 9.4: Algorithms for find, put, and erase for a map stored in a list L.

List based implementation (continued)

Algorithm put(k, v):

Input: A key-value pair (k, v)

Output: The position of the inserted/modified entry

for each position $p \in [L.\text{begin}(), L.\text{end}())$ **do**
  if $p.\text{key}() = k$ **then**
    $*p \leftarrow (k, v)$
    return p {return the position of the modified entry}
$p \leftarrow L.\text{insertBack}((k, v))$
$n \leftarrow n + 1$ {increment variable storing number of entries}
return p {return the position of the inserted entry}

STL map functions (and operators)

size():	Return the number of elements in the map.
empty():	Return true if the map is empty and false otherwise.
find(k):	Find the entry with key k and return an iterator to it; if no such key exists return end.
operator[k]:	Produce a reference to the value of key k; if no such key exists, create a new entry for key k.
insert(pair(k, v)):	Insert pair (k, v), returning an iterator to its position.
erase(k):	Remove the element with key k.
erase(p):	Remove the element referenced by iterator p.
begin():	Return an iterator to the beginning of the map.
end():	Return an iterator just past the end of the map.

An example of STL map in use

```
map<string, int> myMap;                          // a (string,int) map
map<string, int>::iterator p;                    // an iterator to the map
myMap.insert(pair<string, int>("Rob", 28));      // insert ("Rob",28)
myMap["Joe"] = 38;                               // insert("Joe",38)
myMap["Joe"] = 50;                               // change to ("Joe",50)
myMap["Sue"] = 75;                               // insert("Sue",75)
p = myMap.find("Joe");                           // *p = ("Joe",50)
myMap.erase(p);                                  // remove ("Joe",50)
myMap.erase("Sue");                              // remove ("Sue",75)
p = myMap.find("Joe");
if (p == myMap.end()) cout << "nonexistent\n"; // outputs: "nonexistent"
for (p = myMap.begin(); p != myMap.end(); ++p) { // print all entries
  cout << "(" << p->first << "," << p->second << ")\n";
}
```

Reading Material

Section 9.1 of the textbook